

# The Discontinuous Galerkin Method for Hyperbolic Problems on tetrahedral meshes: A posteriori Error Estimation

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SIAM Student Conference 2010  
Virginia Tech

February 20, 2010

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- 5 Conclusion: Summarize results and described future work.

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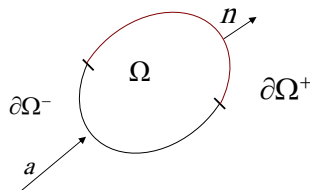
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  - Has a simple communication pattern between elements with a common face that makes it useful for parallel computation.
  - Can handle problems with complex geometries to high order.
  - Does not require continuity across element boundaries
- A posteriori Error Estimation
  - $u - U_h \approx E$
  - Asymptotic behavior of the error
  - Drive Adaptive refinement

# DG formulation and preliminary results

- A model problem

$$\begin{cases} a \cdot \nabla u = f(x, y, z), & (x, y, z) \in \Omega = [0, 1]^3 \\ u|_{\partial\Omega} = g(x, y, z) \end{cases} \quad (1)$$



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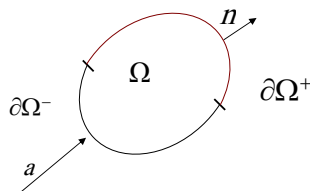
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where

$f$  and  $g$  are selected such that the exact solution  $u \in C^\infty(\Omega)$ .

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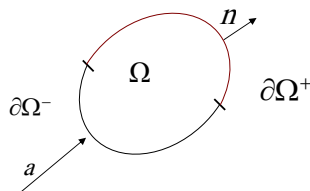
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$\partial\Omega^- = \{(x, y, z) \in \partial\Omega \mid a \cdot n < 0\}$ , is the inflow boundary,

$\partial\Omega^+ = \{(x, y, z) \in \partial\Omega \mid a \cdot n > 0\}$ , is the outflow boundary and

$\partial\Omega^0 = \{(x, y, z) \in \partial\Omega \mid a \cdot n = 0\}$ , is the characteristic boundary.

# DG formulation and preliminary results

- Class and Types of Elements

we partition the domain  $\Omega$  into a regular mesh having  $N$  tetrahedra elements  $\Delta_j$ ,  $j = 1, \dots, N$  of diameter  $h > 0$ , for simplicity We refer to an arbitrary element by  $\Delta$ .

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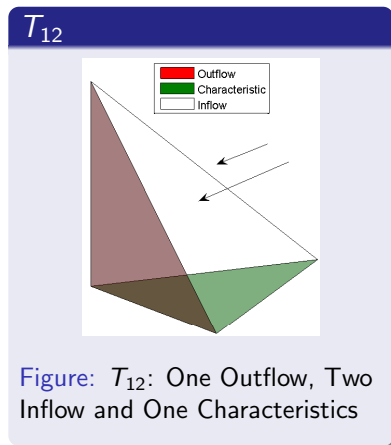
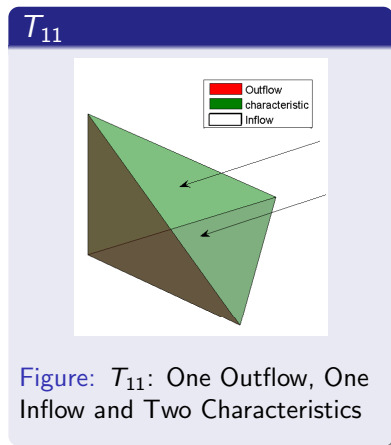
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## Class and Types of elements

	<i>Type I</i>	<i>Type II</i>	<i>Type III</i>
<i>Class I</i>	$T_{11}$	$T_{12}$	$T_{13}$
<i>Class II</i>	$T_{21}$	$T_{22}$	
<i>Class III</i>	$T_{31}$		

# DG formulation and preliminary results

- Some examples for Class and Types of Elements



# DG formulation and preliminary results

- $\mathcal{L}^2$  Orthogonal basis functions

$$\varphi_{q,r}^p(\xi, \eta, \zeta) = \overline{P}_p^{0,0}(\xi, \eta, \zeta) \overline{P}_q^{2p+1,0}(\eta, \zeta) \overline{P}_r^{2p+2q+2,0}(\zeta),$$

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$$\overline{P}_p^{0,0}(\xi, \eta, \zeta) = (1 - \zeta - \eta)^p \hat{P}_p^{0,0}\left(\frac{2\xi}{1 - \eta - \zeta} - 1\right),$$

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$$P_n^{\alpha,\beta}(x) = \frac{(-1)^n}{2^n n!} (1-x)^{-\alpha} (1+x)^{-\beta} \frac{d^n}{dx^n} \left[ (1-x)^{\alpha+n} (1+x)^{\beta+n} \right], \quad \alpha, \beta > -1.$$

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Satisfy  $\mathcal{L}^2$  orthogonality and is complete in the space  $\mathcal{P}_p$

$$\int_0^1 \int_0^{1-\eta} \int_0^{1-\eta-\zeta} \varphi_{ij}^m \varphi_{kl}^n d\zeta d\eta d\xi = c_{ij,kl}^{mn} \delta_{ik} \delta_{jl} \delta_{mn},$$

# DG formulation and preliminary results

## • Standard DG formulation

Multiply (1) by a test function  $v$ , integrate over an  $\Delta$ , apply Stokes' theorem:

$$\begin{aligned} & \int \int_{\Gamma^-} a.nuvd\sigma + \int \int_{\Gamma^+} a.nuvd\sigma + \int \int \int_{\Delta} (-a.\nabla v) u dx dy dz \\ = & \int \int \int_{\Delta} f v dx dy dz, \end{aligned} \tag{2}$$

Approximate  $u$  by a piecewise polynomial function  $U$  s.t  $U|_{\Delta} \in \mathcal{P}_p$ .

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here  $U^- \approx u$  in  $\Gamma^-$ . Let  $\Delta$  such that  $\Gamma^- \subset \partial\Omega^-$ , and subtract (3) from (2) with  $v = V$  to obtain the DG orthogonality conditions for the local error  $\epsilon = u - U$

# DG formulation and preliminary results

## • DG Orthogonality

$$\int \int_{\Gamma^-} a.n\epsilon^- V d\sigma + \int \int_{\Gamma^+} a.n\epsilon V d\sigma + \int \int \int_{\Delta} (-a.\nabla V) \epsilon dx dy dz = 0, \quad (4)$$

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$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} V_2 - V_1 & V_3 - V_1 & V_4 - V_1 \end{pmatrix} \begin{pmatrix} \xi \\ \eta \\ \zeta \end{pmatrix} + V_1$$

map  $\Delta$  with vertices  $V_i = (x_i, y_i, z_i)$ ,  $i = 1, 2, 3, 4$  into the canonical tetrahedron  $\hat{\Delta}$  with vertices  $(0, 0, 0)$ ,  $(1, 0, 0)$ ,  $(0, 1, 0)$  and  $(0, 0, 1)$ .

Then the local error satisfy these orthogonality conditions on the canonical element

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$$\int \int_{\hat{\Gamma}^-} \hat{a}.\hat{n}\hat{\epsilon}^- V d\hat{\sigma} + \int \int_{\hat{\Gamma}^+} \hat{a}.\hat{n}\hat{\epsilon} V d\hat{\sigma} + \int \int \int_{\hat{\Delta}} (-\hat{a}.\nabla \hat{V}) \hat{\epsilon} d\xi d\eta d\zeta = 0, \quad (5)$$

for all  $\hat{V} \in \mathcal{P}_p$ .

# DG formulation and preliminary results

- Preliminary results

If  $u$  is analytic, we can write the local error as a Maclaurin series

$$\epsilon(\xi, \eta, \zeta) = \sum_{k=0}^{\infty} Q_k(\xi, \eta, \zeta) h^k, \text{ where } Q_k \in \mathcal{P}_k \quad (6)$$

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### Lemma

If  $Q_k \in \mathcal{P}_k$ ,  $k = 0, 1, \dots, p$  satisfies

$$\int \int_{\Gamma^+} a \cdot n Q_k V d\sigma + \int \int \int_{\Delta} (-a \cdot \nabla V) Q_k d\xi d\eta d\zeta = 0, \forall V \in \mathcal{P}_p. \quad (7)$$

Then  $Q_k = 0$ ,  $0 \leq k \leq p$ .

Then we obtain the following expression for the local error.

# DG formulation and preliminary results

- Asymptotic behavior of error

## Theorem

Let  $u \in C^\infty(\Delta)$  and  $U \in \mathcal{P}_p(\Delta)$  be the solutions of (1), then the local finite element error can be written as

$$\epsilon(\xi, \eta, \zeta) = \sum_{k=p+1}^{\infty} h^k Q_k(\xi, \eta, \zeta), \quad (8)$$

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$$\begin{aligned}\dim \left\{ \varphi_{j,k}^i, 0 \leq i, j, k \leq p+1 \right\} &= \dim \mathcal{P}_{p+1} \\ &= \frac{(p+2)(p+3)(p+4)}{6} = O(p^3)\end{aligned}$$

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$$\dim \left\{ \chi_{i,j}^{p+1}, 0 \leq i, j \leq p+1 \right\} = \frac{(p+2)(p+3)}{2} = O(p^2)$$

# Basis for the leading term of the local discretization error

## • Basis functions of error II

The leading term  $E$  satisfy these orthogonality conditions

$$\begin{aligned} & \int \int_{\Gamma^-} a \cdot n E^- V d\sigma + \int \int_{\Gamma^+} a \cdot n E V d\sigma \\ & + \int \int \int_{\Delta_e} (a \cdot \nabla E) V dx dy dz = 0, \forall V \in \mathcal{P}_p \end{aligned}$$

where  $E^- = u - U^-$ , we choose  $U|_{\Gamma^-} = U^- = u$ , then  $E^- = 0$ , after mapping to the Canonical element we get

$$\int \int_{\hat{\Gamma}^+} \hat{a} \cdot \hat{n} \hat{E} V d\sigma + \int \int \int_{\hat{\Delta}} (\hat{a} \cdot \nabla \hat{E}) V d\xi d\eta d\zeta = 0, \forall V \in \mathcal{P}_p$$

Let  $\lambda = \frac{\alpha}{\beta}$ ,  $\mu = \frac{\gamma}{\beta}$  where  $(\alpha, \beta, \gamma) = \hat{a}$ .

# Basis for the leading term of the local discretization error

- Example of Basis functions for element of Class I,  $p = 0, 1$

Then the function  $\chi_{ij}^{p+1}$  computed on the reference tetrahedra for each class of elements, using Mathematica, and are given in terms of  $\varphi_{j,k}^i$  as:

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- Class I (where we have one outflow)

$p = 0$	$\begin{aligned}\chi_{0,0}^1 &= \varphi_{0,0}^1 \\ \chi_{1,0}^0 &= \frac{2}{3}\varphi_{0,0}^0 + \varphi_{1,0}^0 \\ \chi_{0,1}^0 &= -\frac{1}{3}\varphi_{0,0}^0 + \varphi_{0,1}^0\end{aligned}$
$p = 1$	$\begin{aligned}\chi_{0,0}^2 &= \varphi_{0,0}^2 \\ \chi_{1,0}^1 &= \frac{4}{5}\varphi_{0,0}^1 + \varphi_{1,0}^1 \\ \chi_{0,1}^1 &= -\frac{1}{5}\varphi_{0,0}^1 + \varphi_{0,1}^1 \\ \chi_{2,0}^0 &= \frac{1}{10}\varphi_{0,1}^0 + \frac{4}{5}\varphi_{1,0}^0 + \varphi_{2,0}^0 \\ \chi_{1,1}^0 &= \frac{3}{5}\varphi_{0,1}^0 - \frac{1}{5}\varphi_{1,0}^0 + \varphi_{1,1}^0 \\ \chi_{0,2}^0 &= -\frac{1}{2}\varphi_{0,1}^0 + \varphi_{0,2}^0\end{aligned}$

Table 1: Basis functions for element of Class I

# Basis for the leading term of the local discretization error

- Example of Basis functions for element of Class II and III,  $p = 0$

- Class II (where we have two outflow)

$p = 0$	$\chi_{0,0}^1 = \varphi_{0,0}^1 + \frac{\lambda}{3\lambda+3}\varphi_{0,0}^0$ $\chi_{1,0}^0 = \varphi_{1,0}^0 + \frac{-\lambda+2}{3\lambda+3}\varphi_{0,0}^0$ $\chi_{0,1}^0 = -\frac{1}{3}\varphi_{0,0}^0 + \varphi_{0,1}^0$
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Table 2: Basis functions for element of *Class II*

- Class III (where we have three outflow)

$p = 0$	$\chi_{0,0}^1 = \varphi_{0,0}^1 + \frac{\lambda}{3\lambda+3\mu+3}\varphi_{0,0}^0$ $\chi_{1,0}^0 = \varphi_{1,0}^0 - \frac{(\lambda-2)}{3\lambda+3\mu+3}\varphi_{0,0}^0$ $\chi_{0,1}^0 = \varphi_{0,1}^0 - \frac{\lambda-3\mu+1}{3\lambda+3\mu+3}\varphi_{0,0}^0$
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Table 3: Basis functions for element of *Class III*

# Computational Examples

- A posteriori error procedure

The DG solution  $U_e$  satisfy on the physical elements  $\Omega_e$

$$\int \int_{\Gamma^-} a \cdot n (\tilde{U}^- - U) V d\sigma + \int \int \int_{\Omega_e} (a \cdot \nabla U) V dx dy dz = \int \int \int_{\Omega_e} f V dx dy dz.$$

and the leading term  $E$  satisfy on

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In this analysis we use the local and global effectivity indices in the  $\mathcal{L}^2$  norm

$$\theta_e = \frac{\|E\|_{\mathcal{L}^2(\Omega_e)}}{\|e\|_{\mathcal{L}^2(\Omega_e)}}, \text{ and } \theta = \frac{\|E\|_{\mathcal{L}^2(\Omega)}}{\|e\|_{\mathcal{L}^2(\Omega)}}$$

Under mesh refinement, the effectivity indices should approach unity.

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- 2 Find the Class and Types of each elements
- 3 Start from elements where  $U^-$  is know in all inflow boundary
- 4 Compute the DG solution  $U_e$  in  $\Omega_e$

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- 7 go to (3)

# Computational Examples

## Structured and Unstructured meshes

### Remark

**i) Structured meshes:** These meshes are obtained by partitioning the domain into  $n^3$  cubes for  $n = 1, 2, 3, 4, 5, 6, 7, 8$  and dividing each cube into five tetrahedrons (where  $h_{\max} = \frac{\sqrt{2}}{n}$ ). Thus, the meshes have  $N = 5 \times n^3 = 40, 135, 320, 625, 1080, 1715$  and  $2560$  tetrahedra elements.

**ii) Unstructured meshes:** These meshes are obtained by COMSOL software for  $h_{\max} = \frac{1}{n}$  (for  $n = 1, 2, 3, 4, 5, 6, 7, 8$ ) with number of elements  $N = 24, 192, 476, 943, 2121, 3731, 5846$  and  $8713$ .

# Computational Examples

- Example of Structured and Unstructured meshes

## Structured meshes

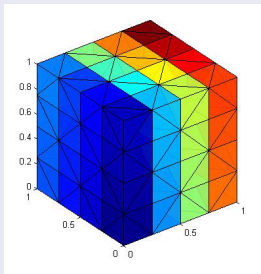


Figure: Tetrahedral mesh with  $N = 5 \times 8^2 = 320$  elements

## Unstructured meshes

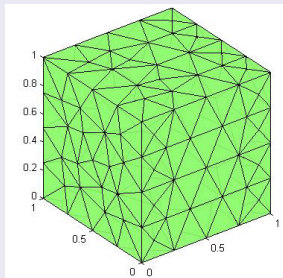


Figure: Tetrahedral meshes obtained by COMSOL with  $N = 953$  elements

# Computational Examples

- Solve Problem 1 in structured meshes

**Example 1:** We consider the following linear hyperbolic problem

$$-3u_x - 7u_y + 13u_z = 3e^{x+y+z}, \quad (x, y, z) \in \Omega = [0, 1]^3,$$

and select the initial and boundary conditions such that the exact solution is

$$u(x, y, z) = e^{x+y+z}.$$

We solve this problem using  $\mathcal{P}_p$ , with the exact boundary condition i.e.  $U^- = u$ , on the first meshes and compare the two methods for  $p = 0, 1, 2, 3$ .

# Computational Examples

- Results of Problem 1 in structured meshes,  $p = 0$

$\mathcal{P}_p$ (Example 1)						
With correction						
$p$	$N$	$\ u - U\ _{2,\Omega}$	<i>Order</i>	$\ u - U - E\ _{2,\Omega}$	<i>Order</i>	$\theta$
	40	1.0279	—	$1.4619e - 01$	—	1.0249
	320	$5.2283e - 01$	1.0155	$4.4524e - 02$	1.7651	1.0257
0	1080	$3.4927e - 01$	1.0031	$2.1341e - 02$	1.8323	1.0215
	2560	$2.6212e - 01$	1.0009	$1.2524e - 02$	1.8594	1.0181
Without correction						
	40	1.1016	—	$8.8975e - 01$	—	0.5326
	320	$5.8671e - 01$	0.9290	$4.9958e - 01$	0.8104	0.4456
0	1080	$4.0105e - 01$	0.9432	$3.4893e - 01$	0.8788	0.4097
	2560	$3.0492e - 01$	0.9549	$2.6829e - 01$	0.9111	0.3901

# Computational Examples

- Results of Problem 1 in structured meshes,  $p = 1$

$\mathcal{P}_p$ (Example 1)						
With correction						
$p$	$N$	$\ u - U\ _{2,\Omega}$	$Order$	$\ u - U - E\ _{2,\Omega}$	$Order$	$\theta$
	40	$1.6430e - 01$	—	$1.1208e - 02$	—	1.0078
1	320	$2.9779e - 02$	2.0298	$1.7188e - 03$	2.7045	1.0100
	1080	$1.3256e - 02$	2.0085	$5.6092e - 04$	2.7975	1.0107
	2560	$7.4596e - 03$	2.0031	$2.4287e - 04$	2.9433	1.0101
Without correction						
	40	$1.4619e - 01$	—	$1.2639e - 01$	—	0.3583
1	320	$4.4524e - 02$	1.7651	$4.0626e - 02$	1.6926	0.2940
	1080	$2.1341e - 02$	1.8323	$1.9748e - 02$	1.7993	0.2835
	2560	$1.2524e - 02$	1.8594	$1.1664e - 02$	1.8371	0.2794

# Computational Examples

- Results of Problem 1 in structured meshes,  $p = 3$

$\mathcal{P}_p$ (Example 1)						
With correction						
$p$	$N$	$\ u - U\ _{2,\Omega}$	$Order$	$\ u - U - E\ _{2,\Omega}$	$Order$	$\theta$
	40	$5.6848e - 04$	—	$3.5351e - 05$	—	1.0088
3	320	$3.6432e - 05$	4.0338	$1.2754e - 06$	4.8473	1.0052
	1080	$7.2110e - 06$	4.0087	$1.7850e - 07$	4.8463	1.0034
	2560	$2.2825e - 06$	4.0035	$4.3753e - 08$	4.9049	1.0026
Without correction						
	40	$7.1418e - 04$	—	$6.2790e - 04$	3.7141	0.37205
3	320	$5.3016e - 05$	3.7605	$4.8864e - 05$	3.6696	0.36086
	1080	$1.1461e - 05$	3.7898	$1.0778e - 05$	3.7375	0.3509
	2560	$3.7927e - 06$	3.8634	$3.6021e - 06$	3.8291	0.3505



# Computational Examples

- Results of Problem 1 in Unstructured meshes,  $p = 2, 3$
- Results for solving Example 1 on the second meshes are given in the following table for  $p = 0, 1, 2, 3$  using the new method.

# Computational Examples

- Results of Problem 1 in Unstructured meshes,  $p = 2, 3$
- Results for solving Example 1 on the second meshes are given in the following table for  $p = 0, 1, 2, 3$  using the new method.

$\mathcal{P}_p$ (Example 1 CM)					
$p = 2$					
$N$	$\ u - U\ _{2,\Omega}$	<i>Order</i>	$\ u - U - E\ _{2,\Omega}$	<i>Order</i>	$\theta$
192	1.6180e - 003	—	7.5291e - 005	—	1.0161
934	4.1263e - 004	3.0445	1.4901e - 005	3.6954	1.0024
3731	1.0915e - 004	3.0376	2.6278e - 006	3.8781	1.0021
8713	4.6621e - 005	3.2370	8.7999e - 007	4.3913	1.0014
$p = 3$					
24	8.3118e - 04	—	5.2796e - 05	—	1.0229
192	5.1438e - 05	4.0142	1.8696e - 06	4.8196	1.0132
934	9.2356e - 06	4.3114	2.9574e - 07	4.7873	1.0020
2121	3.3315e - 06	4.5695	8.7329e - 08	5.4664	1.0020

- Conclusion:
  - Investigated higher-order DGM for scalar first-order hyperbolic problems on tetrahedral meshes.
  - Construct asymptotically correct a posteriori error estimates for discontinuous finite element solutions
  - Write explicitly the basis functions for the error spaces corresponding to the finite element space  $\mathcal{P}_p$ .
  - These a posteriori error estimates tested on several linear problems to show their efficiency and accuracy under mesh refinement for smooth solutions.
  
- Future work

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- Future work
  - Nonlinear problem
  - Transit problem
  - System
  - Other spaces

Thanks!